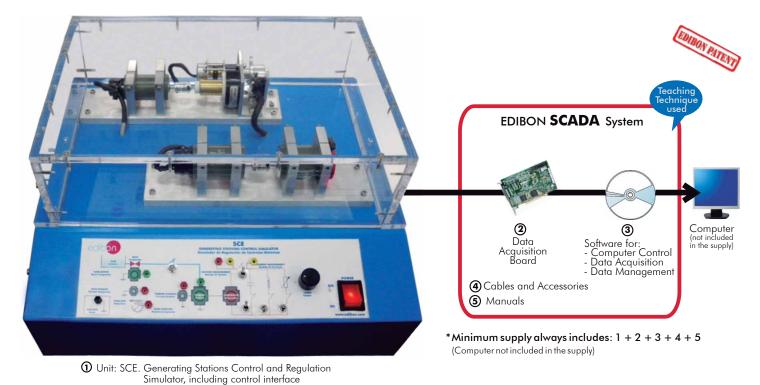


Computer Controlled Generating Stations Control and Regulation Simulator, with SCADA





Key features:

- Advanced Real-Time SCADA.
- Open Control + Multicontrol + Real-Time Control.
- Specialized EDIBON Control Software based on Labview.
- National Instruments Data Acquisition board (250 KS/s, kilo samples per second).
- Calibration exercises, which are included, teach the user how to calibrate a sensor and the importance of checking the accuracy of the sensors before taking measurements.
- Projector and/or electronic whiteboard compatibility allows the unit to be explained and demonstrated to an entire class at one time.
- Capable of doing applied research, real industrial simulation, training courses, etc.
- Remote operation and control by the user and remote control for EDIBON technical support, are always included.
- Totally safe, utilizing 4 safety systems (Mechanical, Electrical, Electronic & Software).
- Designed and manufactured under several quality standards.
- Doptional CAL software helps the user perform calculations and comprehend the
- This unit has been designed for future expansion and integration. A common expansion is the EDIBON Scada-Net (ESN) System which enables multiple students to simultaneously operate many units in a network.

For more information about Key Features, click here:









Certificates ISO 14000 and Management and Audit Scheme (environmental management)



OPEN CONTROL

MULTICONTROL

REAL TIME CONTROL



Certificate (Worlddidac Member)



ISO 9000: Quality Management (for Design, Manufacturing, Commercialization and After-sales service)

DESCRIPTION =

Unit designed to simulate the regulation behaviour of a hydroelectric generating station, as a didactic application with different aspects of regulation, control and simulation.

It is possible to work with this unit in 2 ways:

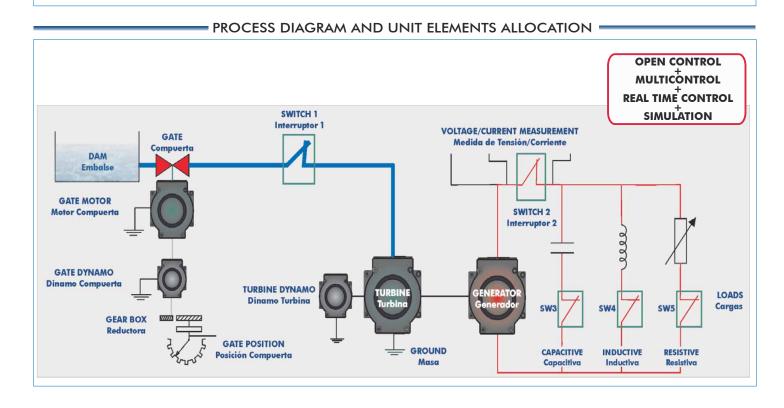
- -REAL mode (continuous or transient analysis).
- -SIMULATED mode.

The unit consists mainly of an interface for the conditioning of input and output signals. For its part, this one will be connected to the computer (through a SCSI wire and a data acquisition board) and to the two subsystems that we try to control:

Gate subsystem.

Turbine-generator subsystem.

The unit has (in the interface) some switches to establish different loads to the generator output and different conditions of the real system.



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Items supplied as standard

① SCE. Unit:

Bench-top unit.

Metallic box and main metallic elements in stainless steel.

Diagram in the front panel with similar distribution to the elements in the real unit.

It is possible to work with this unit in 2 ways:

-REAL mode (continuous or transient analysis).

-SIMULATED mode.

The unit consists mainly of an interface for the conditioning of input and output signals.

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Gate subsystem.

Turbine-generator subsystem.

The unit has (in the interface) some switches to establish different loads to the generator output and different conditions of the real system.

Gate subsystem:

It consists of a motor that controls the gate opening, and some mechanisms that emulate it.

The control tension to command the gate's motor will be range between 0 and 10 volts.

The gate's motor is coupled, by one side, to a dynamo, that will give us a signal proportional to its own rotating velocity, and by the other side to a reduction gear.

The dynamo (Dynamo Gate) gives us a voltage that is proportional to the motor's rotating velocity.

Near the output of the reduction gear there is a potentiometer that gives us an output in volts proportional to the position where it is located, simulating the opening degree of the gate.

Turbine-generator subsystem:

This subsystem will be analyzed separately or linked up with the previous one, achieving that the motor that simulates the turbine turns according to the gate opening percentage.

This turbine is connected with a generator system and with a system of different loads (inductive, capacitive and resistive).

Three loads in parallel are connected at the generator output, that simulate the consumption of the energy distribution system:

Variable resistance (270-770 Ω approx.).

Capacitance (1000 μ F).

Inductance (100 mH).

Control interface.

2 DAB. Data Acquisition Board:

PCI Data acquisition board (National Instruments) to be placed in a computer slot. Bus PCI.

Analog input: Channels = 16 single-ended or 8 differential. Resolution = 16 bits, 1 in 65536.

Sampling rate up to: 250 KS/s (Kilo samples per second). Input range (V) = ± 10 V.

Data transfers=DMA, interrupts, programmed I/O. DMA channels=6.

Analog output: Channels=2. Resolution=16 bits, 1 in 65536. Max. output rate up to: 833 KS/s.

Output range(V)= ± 1 0V. Data transfers=DMA, interrupts, programmed I/0.

Digital Input/Output: Channels=24 inputs/outputs. D0 or DI Sample Clock frequency: 0 to 1 MHz.

Timing: Counter/timers=2. Resolution: Counter/timers: 32 bits.

③ SCE/CCSOF. Computer Control + Data Acquisition + Data Management + Simulation Software:

Compatible with actual Windows operating systems. Graphic and intuitive simulation of the process in screen. Compatible with the industry standards.

Registration and visualization of all process variables in an automatic and simultaneous way. **Flexible, open and multicontrol software**, developed with actual windows graphic systems, acting simultaneously on all process parameters.

Management, processing, comparison and storage of data. Sampling velocity up to 250,000 data per second. Calibration system for the sensors involved in the process.

It allows the graphic representation in real time.

Comparative analysis of the obtained data and modification of the conditions during the process.

Open software, allowing to the teacher to modify texts, instructions. Teacher's and student's passwords to facilitate the teacher's control on the student, and allowing the access to different work levels.

This software has got 2 operating modes:

REAL mode: Through motors, actuators and sensors that the unit includes (continuos, transient).

 ${\bf SIMULATED\ mode: through\ the\ mathematical\ modelization\ of\ the\ motors\ , previously\ mentioned.}$

This unit allows the 30 students of the classroom to visualize simultaneously all results and manipulation of the unit, during the process, by using a projector or an electronic whiteboard.

Cables and Accessories, for normal operation.

(5) Manuals: This unit is supplied with 8 manuals: Required Services, Assembly and Installation, Interface and



SCE. Unit



The second of th

SCE/CCSOF

* References 1 to 5: SCE + DAB + SCE/CCSOF + Cables and Accessories + Manuals are included in the minimum supply, enabling a normal operation.

Additional and optional items to the standard supply

PLC. Industrial Control using PLC (7 and 8):

PLC-PI. PLC Module:

Circuit diagram in the front panel.

Front panel:

Digital inputs(X) and Digital outputs (Y) block:

16 Digital inputs, activated by switches and 16 LEDs for confirmation (red).

14 Digital outputs (through SCSI connector) with 14 LEDs for message (green).

Analog inputs block:

16 Analog inputs (-10V. to + 10V.) (through SCSI connector).

Analog outputs block:

4 Analog outputs (-10V. to +10V) (through SCSI connector).

Touch screen:

High visibility and multiple functions.

Display of a highly visible status.

Recipe function.

Bar graph function.

Flow display function.

Alarm list.

Multi language function.

True type fonts.

Back panel:

Power supply connector.

Fuse 2A.

RS-232 connector to PC.

USB 2.0 connector to PC.

Inside

Power supply outputs: 24 Vdc, 12 Vdc, -12 Vdc, 12 Vdc variable.

Panasonic PLC:

High-speed scan of 0.32 μ sec. for a basic instruction.

Program capacity of 32 Ksteps, with a sufficient comment area.

Power supply input (100 to 240 VAC).

DC input: 16 (24 V DC).

Relay output: 14.

Program capacity: 32 ksteps.

High-speed counter.

Multi-point PID control.

Digital inputs/outputs and analog inputs/outputs Panasonic modules.

Communication RS232 wire, to computer (PC).

®SCE/PLC-SOF. PLC Control Software:

For this particular unit, always included with PLC supply.

Items available on request

SCE/CAL. Computer Aided Learning Software (Results Calculation and Analysis).

 ${\color{red} @}$ SCE/FSS. Faults Simulation System.



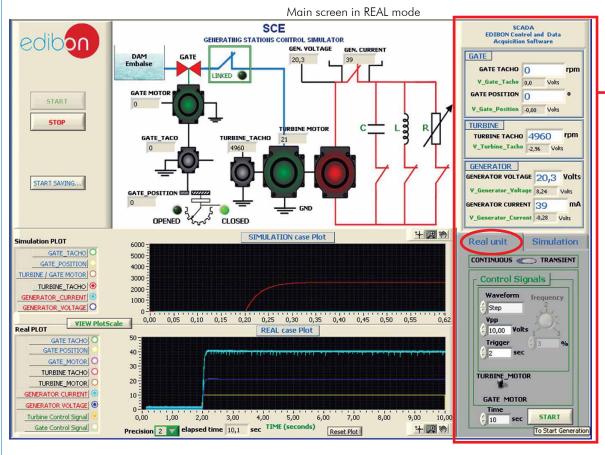
PLC-PI

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Software Main Screens

This software has 2 operating modes:

- 1.- **REAL** mode: We obtain the real response of the system.
- 2.- SIMULATED mode: We obtain the simulated response of the system.

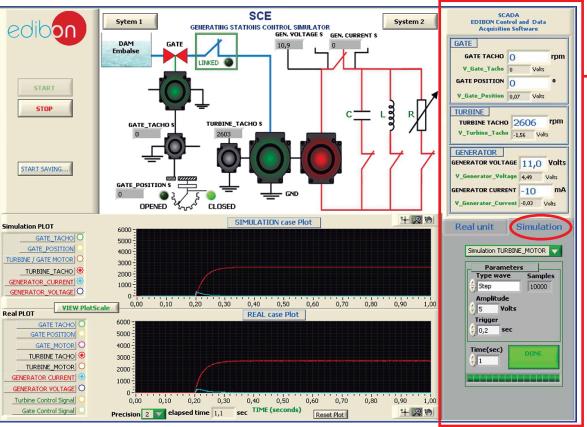


A set of sensors and actuators are available.

We excite the system through the actuators: by the functions generator (sinusoidal, triangular, square signals,...) or continuous signals.

We obtain the system response through the sensors: r.p.m.,voltages and current, given by the system itself.



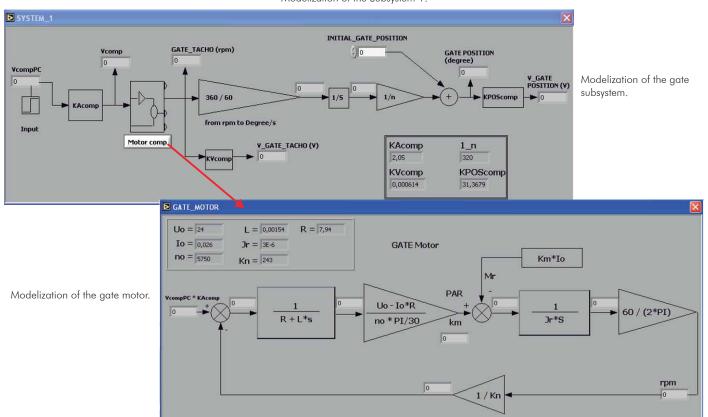


A set of virtual actuators and sensors are available, by which, throught the matemathical model of the system, we obtain the simulated response of the system.

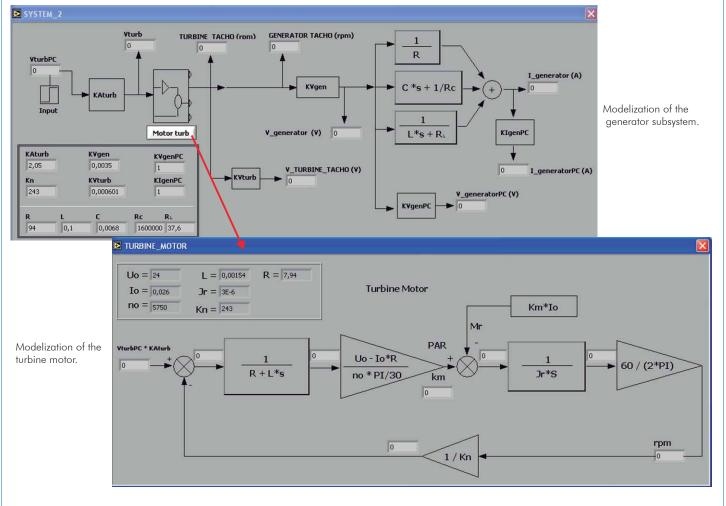
EDIBON Computer Control System (continuation)

Mathematical modelization screens (in SIMULATED mode)

Modelization of the Subsystem 1:

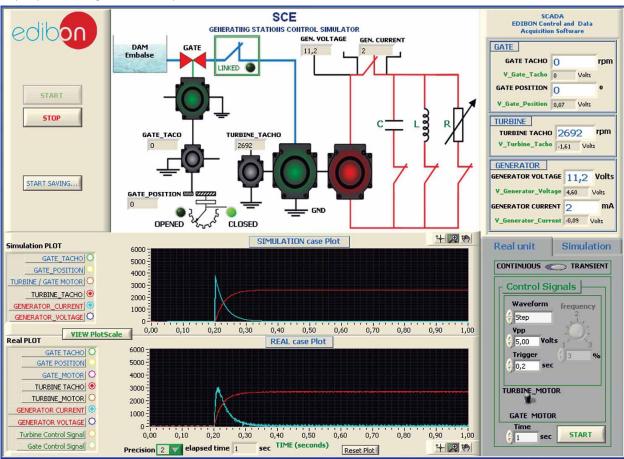


Modelization of the Subsystem 2:

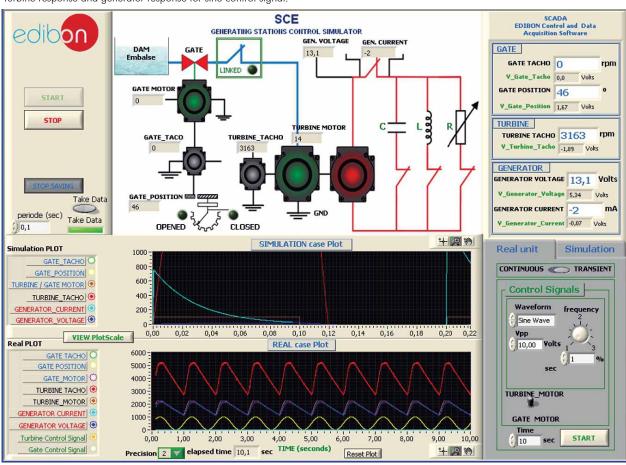


Some typical results screens

Step response of the generator with capacitive load.



Turbine response and generator response for sine control signal.



Some typical results screens

Generator transient response for step control signal.

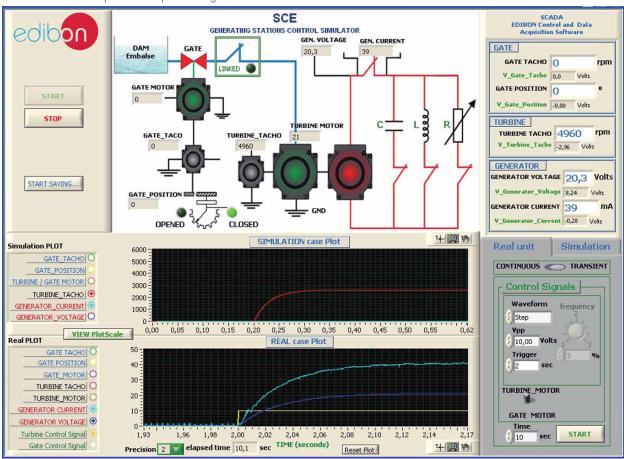
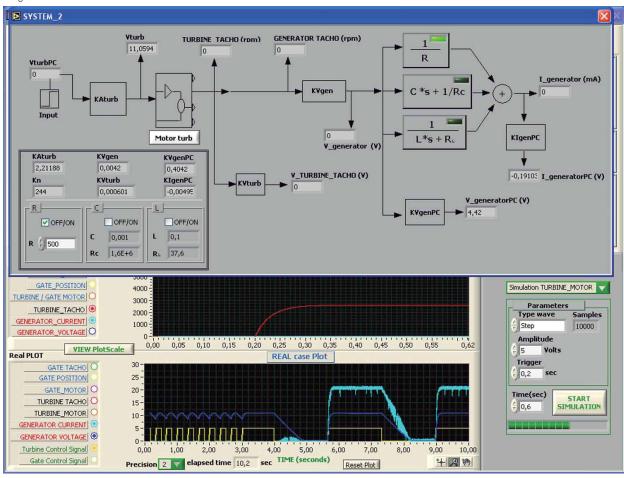


Diagram of the mathematical modelization of the turbine.



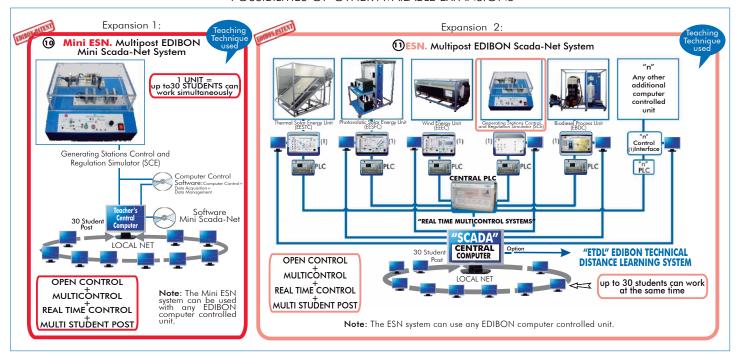
EXERCISES AND PRACTICAL POSSIBILITIES

Some Practical Possibilities of the Unit:

- 1.- Modelization of the motor as a standard motor.
- Modelization of the motor with the constants corrections of the mathematical model.
- 3.- Calculation of the dynamos speed constant.
- 4.- Obtaining of the transient responses of the gate motor.
- 5.- Obtaining of the transient response of the turbine motor.
- 6.- Obtaining of the transient response of the gate simulated motor.
- 7.- Obtaining of the transient response of the turbine simulated motor.
- 8.- Comparative analysis of the transient response of the turbine real motor vs the transient response of the simulated motor for resistive load.
- Comparative analysis of the transient response of the turbine real motor vs the transient response of the simulated motor for capacitive load.
- 10.- Comparative analysis of the transient response of the turbine real motor vs the transient response of the simulated motor for inductive load.
- 11.- Comparative analysis of the response of the gate real motor vs the response of the gate simulated motor for continuous (manually from the computer) control signals.

- 12.- Comparative analysis of the response of the gate real motor vs the response of the gate simulated motor for sinusoidal control signals.
- 13.- Comparative analysis of the response of the gate real motor vs the response of the gate simulated motor for square control signals.
- 14.- Comparative analysis of the response of the gate real motor vs the response of the gate simulated motor for triangular control signals.
- 15.- Comparative analysis of step response between real motor and simulated motor (gate or turbine).

POSSIBILITIES OF OTHER AVAILABLE EXPANSIONS



ORDER INFORMATION

Items supplied as standard

Minimum configuration for normal operation includes:

- ① Unit: SCE. Generating Stations Control and Regulation Simulator.
- ② DAB. Data Acquisition Board.
- ③ SCE/CCSOF. Computer Control + Data Acquisition + Data Management Software.
- @ Cables and Accessories, for normal operation.
- ⑤ Manuals.

* <u>IMPORTANT:</u> Under <u>SCE</u> we always supply all the elements for immediate running as 1, 2, 3, 4, and 5.

Additional and optional items to the standard supply

PLC. Industrial Control using PLC (7 and 8):

- OPCL-PI. PLC Module.
- **O**SCE/PLC-SOF. PLC Control Software.
- **9** SCE/FSS. Faults Simulation System. (Available on request).

Expansions

- Mini ESN. Multipost EDIBON Mini Scada-Net System.
- ⊕ESN. Multipost EDIBON Scada-Net System.

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REQUIRED SERVICES -

-Electrical supply: single-phase, 220V/50 Hz or 110V/60 Hz.

-Computer (PC).

DIMENSIONS & WEIGHTS -

SCE. Unit: -Dimensions: 405 x 350 x 250 mm. approx.

-Weight: 15 Kg. approx.

PLC Module (PLC-PI): -Dimensions: 490 x 330 x 310 mm. approx.

-Weight: 30 Kg. approx.

 $\bigstar \text{Specifications subject to change without previous notice, due to the convenience of improvements of the product.}$



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